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8321 Old Courthouse Road, Suite 200
VIENNA, VIRGINIA 22182-3817
Telephone (703) 761-4100
FACSIMILE (703) 761-2375; (703) 761-2376

APPLICATION FOR UNITED STATES LETTERS PATENT

APPLICANT: Jong-Deok Choi et al.

FOR: STATIC DATARACE DETECTION FOR MULTITHREADED OBJECT-ORIENTED APPLICATIONS

DOCKET NO.: YOR920010366US2

STATIC DATARACE DETECTION FOR MULTITHREADED OBJECT-ORIENTED APPLICATIONS

CROSS-REFERENCE TO RELATED APPLICATIONS

The present application claims priority from U.S. Provisional Patent
Application No. 60/285,087, entitled "STATIC DATARACE DETECTION FOR
MULTITHREADED JAVA APPLICATIONS" having IBM Docket No.
YOR920010366, filed on April 19, 2001, by Choi et al., incorporated herein by reference.

The present application is related to U.S. Patent No. 6,101,524, issued on August 8, 2000, to Choi et al., entitled "DETERMINISTIC REPLAY OF MULTITHREADED APPLICATIONS" having IBM Docket No. YO997-355, and to U.S. Patent Application No. 09/520,008, filed on March 6, 2000, to Choi et al., entitled "DETERMINISTIC REPLAY OF JAVA MULTITHREADED PROGRAMS ON MULTIPROCESSORS" having IBM Docket No. YO999-502, both assigned to the present assignee, and incorporated herein by reference.

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BACKGROUND OF THE INVENTION

Field of the Invention

This invention generally relates to a static datarace detection method and apparatus for multithreaded applications, and more specifically to a static datarace detection method and apparatus for detecting definite dataraces and potential dataraces in multithreaded object-oriented applications written in languages such as JavaTM.

Description of the Related Art

Modern operating system platforms support concurrent multiple threads of execution. However, some of these operating system platforms support concurrent multiple threads without complete scheduling control by the user. For example, operating system platforms that support the JavaTM (hereinafter "Java") Virtual Machine Specification fall into this category. In such systems, each time a Java application runs, the number of instructions executed by a thread in a time interval allocated to the thread may change due to variations in the state of an external operating system. The apparently random number of instructions executed by threads in a time interval introduces non-deterministic program behavior. On a computer system with multiple processors (hereinafter "multiprocessor system"), interactions of different processors through the underlying hardware system cause

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unequal execution speed of threads running on different processors, which also causes non-deterministic program behavior. Other events such as windowing events, network events/messages and general input/output operations may also introduce non-deterministic program behavior.

One problem caused by non-deterministic behavior is a datarace. A datarace may occur when accesses of a shared resource by multiple threads may cause one or more threads to compute incorrect results. Typically, a datarace occurs when (a) multiple threads access the same memory location without ordering constraints among the accesses, and (b) at least one of the accesses is a write access. (Under certain circumstances, condition (b) may not be necessary for exhbiting a data race.)

More specifically, there are four necessary conditions for a datarace to exist between two statements: 1) the statements are executed by different threads; 2) the statements access the same memory location, i.e., the same field in the same object; 3) the synchronization objects used in controlling the execution of the first statement do not overlap with those of the second statement; and 4) there is no explicit ordering between the two statements imposed by explicit language constructs in the program such as thread creation and termination. A datarace may occur between execution instances of two statements or between different execution instances of the same statement by different threads.

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By way of specific example, Figure 6 depicts a timing diagram of two methods, named method foo() and method run(). (Only the details of the methods relevant to the datarace example are shown in Figure 6.) In the example, thread T1 executes method foo() (in the left column). When T1 executes statement S13. thread T2 begins executing method run() (in the right column). Although statement S15 in method foo() is inside a synchronized block starting at S14, statement S21 in method run() is not inside any synchronized block (or method). Therefore, there are no constraints on the order in which statements S15 and S21 can execute. Accordingly, whether S15 or S21 executes first may vary from run to run. However, the program can exhibit different behaviors depending on the order in which S15 and S21 execute. For example, when S21 executes after S15, the value that it reads from p.f is the value written by statement S15. Otherwise, it is the earlier value of p.f. Because thread-switching behavior of a program is non-deterministic, so is the manifestation of dataraces at run-time. Also, as dataraces may happen only infrequently, they may be particularly difficult to identify and may not even be noticed during testing and evaluation of a multithreaded application.

Although manual inspection of instructions is a possible approach for identifying data races, it is a time-consuming and error-prone approach. For example, a test program **mtrt** from the SPECjvm98 benchmark suite contains approximately 8,000 bytecode instructions. This program includes approximately

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30 million distinct instruction pairs, but less than 600 of them are potential dataraces. Previous systems for identifying potential dataraces have relied upon either dynamic datarace detection or static type-analysis. Specifically, as described in "Eraser: A Dynamic Data Race Detector For Multithreaded Programs," by Stefan Savage, et al., <u>ACM Transactions on Computer Systems</u>, Vol. 15, No. 4, November 1997, Pages 391-411, a tool named Eraser has been developed to dynamically determine the existence of dataraces.

However, dynamic determination of dataraces is resource intensive. With complex programs, the amount of data that a dynamic datarace detection tool must monitor can lead to excessive space and/or time consumption. For example, to perform an exhaustive dynamic datarace detection, every resource must be "instrumented," or watched, to determine whether a datarace is actually occurring during the entire course of an application's execution. Reducing the number of resources monitored during dynamic datarace detection, can reduce the set of dataraces detected.

Further, dynamic datarace analysis detects dataraces that actually occur during an execution of a multithreaded application. The result of dynamic datarace analysis is susceptible to the instrumentation perturbation and also to the variation of input data. Accordingly, conventional systems using dynamic datarace detection fail to enable comprehensive and resource efficient identification of dataraces in complex, multithreaded applications.

Pre-existing static datarace detection methods, such as those based on static type analysis, are quite inaccurate. Specifically, as described in "Type-based race detection for Java," by C. Flanagan and S. N. Freund,

Proceedings of the ACM SIGPLAN Conference on Programming Language

Design and Implementation (PLDI) June 2000, pages 219-232, a tool has been developed to statically determine the existence of dataraces based on static type analysis. A fundamental problem with this tool is that it identifies many "false positives" i.e., identifies dataraces that may never be exhibited in any program execution. Further, programmer annotations are required to improve the effectiveness of the tool.

SUMMARY OF THE INVENTION

In view of the above and other problems of the conventional systems and techniques, it is an object of the present invention to provide a more precise static datarace detection method and apparatus for multithreaded applications than pre-existing ones.

It is another object of the invention to provide a system and method for statically identifying dataraces while using fewer system resources than required by conventional datarace detection systems and methods. Specifically, it is an object of the invention to provide a system and method for statically identifying

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dataraces while using fewer system resources than required by dynamic datarace detection systems and methods. It is a further object of the invention to provide a system and method for statically identifying dataraces with greater accuracy than conventional datarace detection systems and methods, such as static datarace detection systems and methods based on static type analysis.

In a first aspect of the present invention, a method is provided for statically detecting a datarace in a multithreaded application, the method including inputting a set of input information, processing the set of input information, and outputting a Statement Conflict Set (SCS) that identifies the statements whose execution instances may cause a datarace. The method need not execute the multithreaded application. The input information may include a multithreaded context graph (MCG), wherein the MCG comprises an interprocedural call graph having each of a plurality of synchronized blocks and methods as separate nodes. The multithreaded application may be an application written in an object oriented language, such as Java. The method may further include performing dynamic datarace detection on the outputted SCS. (The availability of an SCS can enable dynamic datarace detection to be perfomed more efficiently.)

In another embodiment of the present invention, a computer processing system includes an input interface, an output interface, a storage medium comprising an application and meta-information relating to the application, and a processor configured to receive the application and the meta-information, process

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the application and the meta-information without executing the application, and determine a statement conflict set (SCS) for the application.

In still another embodiment of the present invention, a computer program product includes computer readable medium having computer code embodied therein for statically detecting a datarace in a multithreaded application. The computer readable medium has a computer code embodied therein for statically detecting a datarace in a multithreaded application. The computer program product includes computer readable program code devices configured to receive the application and the meta-information, computer readable program code devices configured to process the application and the meta-information without executing the application, and computer readable program code devices configured to determine a statement conflict set (SCS) for the application.

The present invention detects dataraces by statically analyzing a mutlithreaded application without executing it. By not executing the application in order to detect dataraces, the present invention has the advantage of not being affected by the instrumentation or the choice of input data, as compared with conventional dynamic datarace detection.

The invention statically detects definite dataraces (i.e., dataraces which will definitely occur in all program executions), and also detects potential dataraces (i.e., dataraces which may occur in some execution instance). The invention identifies four necessary conditions for a datarace to occur between an

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execution of statement S1 and S2, both involving a memory access: (1) they are performed by different threads; (2) they access the same memory location; (3) the synchronization objects used in controlling the execution of the first statement do not overlap with those of the second statement; and (4) there exists no further timing constraint imposed by the program on the execution of the two statements due to thread creation and termination ordering.

To determine whether these four conditions are met for any two statements in an application, the invention uses two types of alias information: must-alias and may-alias. How to compute must and may alias information is well understood to those of ordinary skill in the art. Specifically, the following documents each describe how to compute may-alias information: "Efficient flow-sensitive interprocedural computation of pointer-induced aliases and side effects," by J.-D. Choi, et al, <u>Proceedings of the ACM 20th Symposium on Principles of Programming Languages (POPL)</u> January 1993, pages 232 - 245;

"Pointer-induced aliasing: a problem taxonomy," by W. Landi and B. G. Ryder,

Proceedings of the ACM 18th Symposium on Principles of Programming

Languages (POPL) January 1991, pages 93 - 103. The following document

describes how to compute must-alias information: "An extended form of must

alias analysis for dynamic allocation," by R. Altucher and W. Landi, Proceedings

of the ACM 22nd Symposium on Principles of Programming Languages (POPL)

January 1995, pages 74-84.

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In addition to using alias information, the invention includes a new algorithm and a new interprocedural program representation, called the multithreaded context graph (MCG), for verifying the first, third and fourth conditions mentioned above. The MCG is similar to the interprocedural call graph (CG), which is a well known program representation from the prior art. In the CG, each node represents a method, and each edge from one method to another represents a callsite in the first method that can potentially invoke the second method.

The invention works by first identifying synchronized methods and blocks (collectively referred to as synchronization nodes) as the principal means to impose timing constraints between executions of different statements. The invention then represents synchronized blocks, as well as synchronized methods, as separate nodes in the MCG. One major difference between CG and MCG is that synchronized blocks and synchronized methods are represented as separate nodes in MCG. For each statement, the invention then identifies the set of objects used as synchronization arguments to synchronize methods and blocks along the MCG paths from the root method of the thread executing the statement to the statement. This set of objects, called the synchronization objects, of each statement is used in determining whether there exists a timing constraint due to synchronization between the executions of two statements: if statements S1 and S2 have no common synchronization objects, there exists no timing constraint

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due to synchronization between their executions. The invention also exploits additional operations, such as thread creation/termination/rendezvous, to identify additional timing constraints between executions of statements. The MCG has edges for these additional operations.

The invention further includes a framework that identifies a spectrum of dataraces from definite dataraces to potential dataraces, by employing different combinations of must-alias and may-alias information, without changing the mechanisms used to determine whether the aforementioned four conditions are met.

BRIEF DESCRIPTION OF THE DRAWINGS

The foregoing and other objects, aspects and advantages will be better understood from the following detailed description of a preferred embodiment of the invention with reference to the drawings, in which:

Figure 1 illustrates an exemplary computer processing system on which the present invention may be implemented;

Figure 2 illustrates a flowchart of the method of statically detecting a datarace in a multithreaded application, with an optional step (250) for using the static analysis results in dynamic datarace detection;

Figure 3 illustrates a flowchart for processing a multithreaded context

20 graph (MCG) to determine a statement conflict set (SCS);

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Figure 4 illustrates a flowchart for computing a node conflict set (NCS);
Figure 5 illustrates a media for storing a computer program product; and
Figure 6 represents a program segment having two threads.

DETAILED DESCRIPTION OF A PREFERRED EMBODIMENT OF THE INVENTION

Referring to Figure 1, there is shown a block diagram of a computer system 100 on which a preferred embodiment of the present invention operates.

In one embodiment, a system in accordance with the present invention includes an input interface, an output interface, a storage medium comprising the application and meta-information relating to the application, and a processor configured to receive the application and the meta-information, process the application and the meta-information without executing the application, and determine a statement conflict set (SCS) for the application.

As an example, the computer system 100 may include one or more application programs 102 and an operating system 108 that operate on a computer platform 104. The platform 104 includes a hardware unit 112 that includes one or more central processing units (CPUs) 116 (which are typically referred to as CPUs/processors), a random access memory (RAM) 114, and an input/output interface 118.

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Various peripheral components may be connected to the computer platform 104 including a terminal 126, a data storage device 130, and a printing device 134. The operating system 108 coordinates the operation of the various components or the computer system 100. An example of computer system 100 is the IBM System/6000® (RISC System/6000® is a trademark of the IBM Corporation). It is readily understood that those skilled in the computer arts will be familiar with many equivalent computer systems to computer system 100.

The operating system 108 of the present invention provides multithreading capabilities wherein multiple concurrent threads of control are dispatched within a single shared address space. Examples include the built-in thread support available within Java Virtual Machines, Microsoft's Windows NT® operating system, and the POSIX threads package that is available on many operating systems, for instance as the package of IBM's AIX® (AIX® is a registered trademark of the IBM Corporation) operating system.

Referring now to Figure 2, there is a flowchart of the method of statically detecting a datarace in a multithreaded application. The method includes inputting a set of input information 220, processing the set of input information 230, and outputting a statement conflict set 240. Each element of the statement conflict set identifies a datarace that may occur in some execution. The method may additionally include performing dynamic datarace detection 250 by refining

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the outputted SCS, 240, to a specific execution. Each element of the method is now described in greater detail.

Inputting information 220 may include inputting an MCG. This MCG, as described above, is a CG that additionally represents synchronized blocks, as well as synchronized methods, as separate nodes. The input information may also include the bytecodes that collectively comprise the multi-threaded application, such as a Java® application. Additional information may also be input to facilitate the static determination of dataraces.

Processing the MCG to determine a statement conflict set (SCS) 230 is depicted in greater detail in Figure 3, which includes computing a node conflict set (NCS) and computing the SCS by identifying pairs of conflicting statements in the NCS. Figure 3 is described in greater detail below.

Outputting the SCS 240 includes outputting the SCS in a human-readable, computer-readable, or other format. For example, outputting the SCS 240 may include displaying the SCS on an output device, such as a display or a printer, as shown in Figure 1. Additionally, outputting the SCS may include sending the SCS to a communication interface, such as a MODEM interface, or a storage media interface, such as a secondary storage interface.

In one embodiment, the analysis is implemented without executing the corresponding mutlithreaded application, and stops at step 240. In another

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embodiment, the method executes the program in step 250, and refines the SCS by performing dynamic datarace detection.

Figure 3 illustrates a flowchart for processing a multithreaded context graph (MCG) to determine a statement conflict set (SCS). This processing involves computing a node conflict set (NCS) 320 and, from this NCS, computing the SCS by determining pairs of conflicting statements in the NCS 330. Each of the elements of the method is described in greater detail below.

Computing an NCS 320 involves each of the operations depicted in Figure 4. Specifically, computing an NCS 320 first involves initializing a synchronization object set for each of a plurality of MCG nodes 420. This is done through a forward worklist data-flow analysis operating over the MCG starting at a root node and following intrathread edges of the MCG. The domain of the data-flow fact sets is synchronization objects. Given a node n in the MCG, the synchronization object set at entry to n (SyncObj.n.i) and the synchronization object set at exit from n (SyncObj.n.o) may be defined by the following expressions:

$$SyncObj.n.o = (SyncObj.n.i) \cup (n.SyncObj)$$

SyncObj.n.i =
$$\bigwedge_p \text{SyncObj.p.o}$$
, $\forall p \in \text{Predecessors}(n)$,

Where the operator \land represents set union (\bigcup) for computing definite dataraces, and set intersection () for computing potential dataraces. Also, n.SyncObj is 20 the set of synchronization objects introduced at MCG node n. (The set is YOR920010366US2

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non-empty only if node n represents a synchronized method or synchronized block.)

Once the synchronization object sets of each MCG node have been initialized at 420, a traversal of MCG is performed. Specifically, the traversal involves identifying all reachable conflicting node pairs for each distinct pair of thread-root nodes in the MCG 430 and identifying all reachable conflicting node pairs for each thread-root node in the MCG that is invokeable by more than one thread 440. A thread-root node is a node on MCG that corresponds to the statement starting the execution of a thread. In Java, it corresponds to an MCG node corresponding to the run () method of a Runnable object such that the node has an interprocedural edge to it from a node corresponding to an invocation of a start () method of a Runnable object. A node on MCG is reachable from a thread-root node if there exists a path to it from the thread-root node on MCG. Two nodes n1 and n2 are said to be conflicting nodes if n1 contains an object reference r1 and n2 contains an object reference r2 such that the SameAccessObj(r1, r2) predicate is true. The SameAccessObj(r1, r2) predicate itself is defined as follows:

Let MustAlias(p) and MayAlias(p) be the set of must aliases and the set of may aliases of an object reference p, respectively.

For definite datarace,

SameAccessObj $(r1, r2) = (MustAlias(r1) \cap MustAlias(r2)).$

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For potential datarace,

SameAccessObj $(r1, r2) = (MayAlias(r1) \cap MayAlias(r2)).$

The traversal of 430 begins with pairs of distinct thread-root nodes on the

MCG, which implies that they must be executed by distinct threads. The traversal at 440 begins with a single thread-root node, and uses the
MultipleTheadInstances predicate/relation to determine if the thread-root node can be invoked more than once (as a new thread) in a single application execution.
Both 430 and 440 accumulate node-pairs in the NCS. The

MultipleTheadInstances predicate for a thread-root node R is defined as follows:

 $\label{eq:MultipleThreadInstances} \begin{aligned} & \textbf{MultipleThreadInstances}(R.\textbf{this}) = MustAlias(this) = \{\}, \\ & \text{where } R.\textbf{this} \text{ is the } \textbf{this} \text{ pointer of } R. \end{aligned}$

Returning to Figure 3, after the NCS has been determined, the method proceeds to computing the SCS by identifying pairs of conflicting statements in the NCS 330. More particularly, for each pair of MCG nodes in the NCS, the object references within each node are examined to determine whether they represent a datarace or not by using the **SameAccessObj** relation. Escape analysis is employed to compensate for imprecision of alias analysis. Escape analysis checks if an object may be visible to more than one thread (this can happen if the object's reference is saved in a static field or in a field of an object that implements the Runnable interface). Then, even if alias analysis results suggest

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that the same object may be accessed in two statements executable by different threads, the two statements should not be added to the SCS if the object does not escape its creating thread.

One technique of determining whether a pair of MCG nodes from the NCS belongs in the SCS is to first check that the accesses are to the same location in the object (e.g., same field of a non-array object). If they are, there is a potential datarace. However, if two accesses to fields of the synchronization arguments (the **this** reference in a synchronized method, or the argument of the synchronized statement which opens a synchronized block) are made, there is no datarace. By eliminating nodes wherein the two accesses are to fields of the synchronization arguments, the present invention is able to improve the precision of datarace analysis when testing accesses to synchronization objects.

In a preferred embodiment, potential dataraces are detected using the following precise definitions of various types of aliasing between a reference expression and an object. For a given reference variable p and statement S, a reference expression p(S) denotes a set of values that p holds at statement S. Must and may alias information may be determined by any conventional method, including methods developed in the future.

Regarding the thread objects, an object has a must-alias thread object if it has a single thread object that is a must-alias object, and an object has a may-alias thread object if it has a single thread object that is a may-alias object or a

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must-alias object. The following predicates are used to define DefSameThreadObj and PossSameThreadObj:

- (1) DefSameThreadObj(p(S.i), q(S.j)) = (MustThreadObj(p(S.i)) \cap MustThreadObj(p(S.j))) \neq { }
- 5 (2) PossSameThreadObj(p(S.i), q(S.j)) = (MayThreadObj(p(S.i)) \cap MayThreadObj(p(S.j))) \neq { }

The access objects of a reference expression are the alias objects of the reference expression. They represent the set of dynamic objects any one of which might be accessed at time of execution. MustAccessObjects(p(S)) and

MayAccessObjects(p(S)) denote the set of must-alias objects and may-alias objects of p(S), respectively. The following predicates are used to define DefSameAccessObj and PossSameAccessObj:

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(3) DefSameAccessObj(p(S.i),q(S.j)) = (MustAccessObj(p(S.i))

\cap MustAccessObj(p(S.j)) \neq { } )

\wedge (p(S.i) and q(S.j) access the same field)

\wedge (p(S.i) or q(S.j) is a write)
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(4) PossDefSameAccessObj(p(S.i),q(S.j)) = (MayAccessObj(p(S.i)) \cap MayAccessObj(p(S.j)) \neq { }) \wedge (p(S.i) and q(S.j) access the same field) \wedge (p(S.i) or q(S.j) is a write)

As described above, under some memory models, a read-read pair may also cause a datarace. Accordingly, the last condition of the above two predicates may be eliminated or modified to suit a particular memory model.

The synchronization objects of two statements allow the determination of whether two statements (or two executions of a single statement) executed by two

different threads are synchronized with respect to each other via the synchronization objects (e.g., of synchronized methods and synchronized blocks).

If two expressions always execute within a lifetime of a synchronized method or block invoked on the same must-alias object, then the expressions are definitely synchronized. Similarly, if two expressions may execute within a lifetime of a synchronized method or block invoked on the same may-alias object, then the expressions may be synchronized. The two situations are used to define predicates DefSync and PossSync, respectively.

Additionally, the expression DefExecutionStmt(S) is true if and only if the execution statement S must execute.

Potential dataraces are detected by using an IsPotentialDR relation and definite dataraces are detected by using an IsDefiniteDR relation. The IsPotentialDR relation is preferably defined as:

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(5) IsPotentialDR(p(S.i), q(S.j)) =

15 (6) \neg (DefSameThreadObj(p(S.i), q(S.j)))

(7) \land (PossSameAccessObj(p(S.i), q(S.j)))
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(8) $\land \neg (DefSync(p(S.i), q(S.j)))$

The IsDefiniteDR relation is preferably defined as:

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In each of these relations, ¬ represents the negation of an expression and ∧ represents the conjunction of an expression. Accordingly, regarding the IsPotentialDR, equation (6) states that the two reference expressions might be executed by different threads (negation of DefSameThreadObj), Equation (7) states that the two reference expressions might access the same field of the same object, and Equation (8) states that the two reference expressions might not be mutually synchronized (negation of DefSync).

Further, regarding the IsDefiniteDR, Equation (10) states that the two reference expressions cannot be executed by the same thread (negation of PossSameThreadObj), Equation (11) states that the two reference expressions must access the same field of the same object, and Equation (12) states that the two reference expressions cannot be mutually synchronized (negation of PossSync). Additionally, IsDefiniteDR further determines whether each of the statements must execute using Equations (13) and (14).

Between the extremes of definite and potential datarace analysis, a number of intermediate methodologies of analysis are also possible. For example, a plausible datarace may be defined as:

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IsPlausibleDR(p(S.i), q(S.j)) =
\neg (DefSameThreadObj(p(S.i), q(S.j)))
\wedge (DefSameAccessObj(p(S.i), q(S.j)))
\wedge \neg (PossSync(p(S.i), q(S.j)))
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Other types of relations are possible based on the input information available, the degree of certainty in detecting a datarace required, and other factors.

Figure 5 illustrates a computer program product, including computer readable medium 500 having computer code embodied therein for statically detecting a datarace in a multithreaded application. The computer program product includes computer readable program code devices configured to receive the application and the meta-information, computer readable program code devices configured to process the application and the meta-information without executing the application, and computer readable program code devices configured to determine a statement conflict set (SCS) for the application.

As an example, this method may be implemented in the particular hardware environment discussed above with regard to Figure 1. Such a method may be implemented, for example, by operating the CPU 116 (Figure 1), to execute a sequence of machine-readable instructions. These instructions may reside in various types of signal-bearing media.

Thus, this aspect of the present invention is directed to a programmed product, comprising signal-bearing media tangibly embodying a program of machine-readable instructions executable by a digital data processor incorporating the CPU 2 and hardware above, to perform a method detecting dataraces in multithreaded object-oriented programs.

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This signal-bearing media may include, for example, RAM 114 contained externally or within the CPU 116, as represented by fast-access storage for example. Alternatively, the instructions may be contained in another signal-bearing media, such as data storage 130 (Figure 1) or a magnetic data storage diskette 500 (Figure 5), directly or indirectly accessible by the CPU 116.

Whether contained in the diskette 500, the computer 100, or elsewhere, the instructions may be stored on a variety of computer readable medium having computer code embodied therein for statically detecting a datarace in a multithreaded application, such as DASD storage (e.g., a conventional "hard drive" or a RAID array), magnetic tape, electronic read-only memory (e.g., ROM, EPROM, or EEPROM), an optical storage device (e.g. CD-ROM, WORM, DVD, digital optical tape, etc.), paper "punch" cards, or other suitable signal-bearing media including transmission media such as digital and analog and communication links and wireless. In an illustrative embodiment of the invention, the machine-readable instructions may comprise bytecodes corresponding to a mutlithreaded Java application, software object code compiled from a language such as "C", etc.

In one embodiment of the present invention, static datarace detection is used in conjunction with dynamic datarace detection. For example, given a program that has a predetermined number of statements, static datarace detection is used to identify a first datarace set comprising statements that may be dataraces,

dynamic datarace detection is then used to identify a third number of statements that actually cause dataraces on a set of executions.

While the invention has been described in terms of a preferred embodiment, those skilled in the art will recognize that the invention can be practiced with modification within the spirit and scope of the appended claims.